A Reflective Architecture for an Adaptable Object-Oriented Operating System Based on C++

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1 Introduction

Todays operating systems have to support applications and hardware with highly specialized requirements. Traditional all-purpose operating systems can't be an optimal runtime environment for all the diverse applications. Therefore, instead of huge universal operating systems small tailored systems are needed to provide exactly the services and properties really required in a concrete situation.

In the field of software development the object-oriented paradigm has been widely accepted as powerful method to achieve adaptability. Hence, if the set of required properties remains the same during the whole runtime of a system, object-oriented frameworks like PEACE [Schröder-Preikschat93], Choices [Russo91] or Tigger [Cahill94] are well suitable to manufacture tailored operating systems. However, once booted, such a system can not be adapted to changed requirements (\sim static adaptability). If rebooting is not acceptable (due to the required availability or the effort for rebooting) a way for dealing with future requirements by dynamic modification of the running system is needed $(\sim$ dynamic adaptability). Several commercial systems (Solaris, AIX, etc.) and a lot of research systems (Spin [Bershad95], Bridge [Lucco94], Apertos [Yokote93]) are already dynamically modiable. Also some of the named frameworks have been extended to support dynamic adaptation (e. g. PEACE [Schmidt95] and Choices [Madany92]). However, possible modications are often highly restricted and complicated to perform. Even though a system has been structured in an object-oriented manner and implemented in an ob ject-oriented language, during runtime usually nothing of that structuring information is still available. After compiling and linking the system, there is no knowledge about classes, class membership, etc. Therefore, some operating systems are constructed as ob ject management systems (e. g. BirliX [Hartig90] or Clouds [Dasgupta91]). They are able to manage objects in various ways and to use ob jects as the basic components for service providing, adaptation, migration, etc. However, the resulting object structure differs considerably from the structures used during software development (source-code level). Because of the often very heavy-weight objects (private address space and own thread of control) no fine-grained adaptation is possible.

In the CHEOPS¹ pro ject we are applying an approach for a re
ective, ob ject-oriented system architecture, to support fine-grained, dynamic adaptability. It is based on the idea to close the

[&]quot;CHEOPS - CHemnitz OPerating System

gap between models and abstractions used during development (design and implementation) and the identifiable entities in the running system (see also [CHEOPS96]). By retaining most of the structuring information about classes, ob jects, and the relations between them it should be possible to perform the same extensions and modications as have been done to the system's description (source code) within the running system itself.

The second section of this paper presents our point of view to the underlying concepts: reflection and runtime representations of abstractions. After that, the class-ob ject architecture of CHEOPS is introduced. Section 4 gives a short impression about the implementation of this architecture based on $C++$. Finally other related and future work is discussed.

2 Reflection and runtime representations of abstractions

A clear and well comprehensible system architecture forms the general basis for each modification of a system. To perform the same steps of adaptation in the running system as have been done at source-code level we need an open architecture that fulfills the following requirements:

- The identifiable objects in the running system have to be the same (in granularity and functionality) as at description level, modeled by means of an ob ject-oriented programming language.
- Meta-level informations as
	- $-$ available classes,
	- $-$ class merarchy (*is-a* relations),
	- u *sing-*relations,
	- $-$ correlation of objects to classes,
	- $-$ and animity relations between objects

have to be still available in the running system.

 \bullet *Meta functionality* as creation, destruction, storage and life-time management of objects as well as object invocation mechanisms (all usually performed by the run-time environment) has to be opened up and assigned to identiable entities in the system.

The solution is based on the concepts of reflection and run-time representations of abstractions. Reflection has been introduced by Brian Smith [Smith82]. Later the ideas have been broadened to the ob ject-oriented world by Pattie Maes [Maes87]. The concept can be shortly outlined as the ability of ob jects (so called base-level ob jects) to know about their run-time environment (also called infrastructure or meta level) and to be able to make that environment to the matter of computation itself. In this way ob jects are able to change their (meta-)properties by modifying the meta level. In an ob ject-oriented system the meta level itself may be also composed by ob jects.

Although the most work in the field of reflection has been done related to several programming languages (e. g. the meta-ob ject protocol of CLOS [Kizcales93]) the Apertos-OS has shown that the concept is also suitable for an operating systems architecture [Lea95]. In our opinion the precondition for applying reflection within a running system is the availability of identifiable system

components as run-time representations of the meta-level abstractions used during development. According to that we propose to transform classes into the running system and to assign them all the tasks resultant from the requirements above.

3 The Class-Ob ject Architecture of CHEOPS

Dynamic adaptation in CHEOPS is done by adding or exchanging classes and objects during the system's runtime. Therefore, as explained above we need a representation of classes within the running system, the so called *class objects*. To distinguish the base-level objects from the class objects the former are called *regular objects* (see Fig. 2). A class object is an identifiable ob ject within the system. One class ob ject exists for each description-level class in the system. The class object manages the objects belonging to its class. and is responsible for:

- creation and destruction of objects,
- ob ject management (registering, localization),
- service negotiation,
- access control (e. g. by access control lists or capabilities),
- supporting ob ject exchange by using the knowledge about the class hierarchy (abstract classes, polymorphism).

According to our basic architecture, class ob jects are part of the infrastructure of regular ob jects and therefore influence their meta properties. To modify these meta properties we would have to modify the class objects. For example, if object A invokes a service of object B , the real invocation has to be performed by the infrastructure, precisely by the class ob ject of ob ject B. Dependent on the class ob ject, ob ject invocation will be performed by a simple call, by a remote procedure call (RPC) , or by sending a message, etc. To A and B this can be absolutely transparent. The functionality for performing ob ject invocation could be modied, for instance to add access control or parameter conversion, without any notication to the communicating ob jects.

Class ob jects are specic for each class. As each ob ject is described by its class, for each class object a class description, the class-object class (COC), exists as well (\sim meta-meta level). Based on the class definition of regular objects, this class-object class is generated automatically (at source code level) by the COC-generator.

Figure 1. The COC-generator

The COC-generator creates a class-ob ject class, which is able to deal with the basic tasks of the class ob ject. To extend or to change that functionality, the developer could specialize the class-ob ject class by derivation.

Class-ob jects can be added or removed to/from the system dynamically. Loading classes and creating class ob jects is based on dynamic linking and supported by the so called class-object manager (COM).

Figure 2. The Class-Ob ject Architecture

The COM exists right from the start within the system and is responsible for:

- \bullet loading new classes (loading the class and the class-object class, creating the class object),
- removing classes.
- exchanging classes,
- managing the class hierarchy.

While adding a new class is a simple kind of extension (always possible), removing a class is only allowed, if currently no ob jects of that class exist. Exchanging classes can be used, for example, for correction of programming errors in an existing class. In this case the class object of the old class has to provide a service to determine and store the current state of all its ob jects. The new class ob ject has to use these data to reconstruct all ob jects. This kind of services is not part of the COC created by the current version of the COC-generator and have to be added by specialization of the COC.

Similar approaches have been already used in other systems, e. g. in SmallTalk [Goldberg83], where it is possible to create hierarchies of classes and meta classes. However, these systems are working by source code interpretation and, consequently, are mostly too inefficient to be used within an operating system's kernel. Therefore our approach is based on using a "compiler based", ob ject-oriented programming language.

4 Realization Based on C++

4.1Language and Restrictions

The realization of the shown approach is based on the C_{++} programming language. The decision to use this language was influenced, among others, by the following advantages:

- \bullet C++ compilers and appropriate development tools (e.g. class browsers) are available for a lot of hardware platforms,
- a lot of implementations in the field of system software and operating systems (e. g. Choices) have been done in $C++$ and show its suitability for constructing efficient systems.

Dynamic adaption in CHEOPS is based on adding, removing or exchanging classes and ob jects. If a new created ob ject of a derived class has to substitute an old one, the new ob ject generally can't be stored at the same place, because of different object sizes. Furthermore, objects have to be able to migrate into other infrastructures to change their meta properties. Therefore, location $transport$ for all those objects is needed. To avoid direct access to objects and influenced by the idea to use the $C++-calling$ mechanism for virtual methods to implement our alternative ob ject invocation mechanism we have decided to make some restrictions to the used language:

- no public data members are allowed,
- all methods have to be virtual.
- all ob jects are created dynamically,

r urthermore, because of the resulting equivocations- and their tricky implementation no multiple inheritance is allowed.

4.2Implementation

Basics

The platform of our implementation is formed by the CHEOPS kernel. It is running standalone on Intel-based PC's (protected mode) and provides the basic functionality for memory management, thread management and message passing. On that base the class-ob ject manager runs as kernel thread. To be able to load and reload classes during runtime it contains a small set of functions to support the dynamic linking process based on ELF's (Executable and Linking Format) position-independent code.

The COC-generator was implemented by using yacc and lex. The current prototype parses not the complete $C++$ syntax and expects syntactical correct code. As all the other necessary development tools it runs on top of Linux. By using an implemented communication mechanism (based on UDP) the COM is able to communicate with an special module-loader process to transfer compiled ob ject modules into the CHEOPS kernel (see Fig 3). In this way development and first testing can be done on top of Linux". After that, the object module is transfered to the CHEOPS-kernel and the modications are performed dynamically. One of the resultant advantages is the very short turn-around time during the incremental kernel development, because frequent rebooting is not necessary.

⁻caused by same member names within different base classes

The first prototypes of COC-generator and also the class-object manager were running on top of Solaris and later Linux. That testing environment is still used for testing new code.

Figure 3. Loading Ob ject Modules into the CHEOPS kernel

However, the system developer has to do several steps to add a new class to the system. As usual the developer has to create a class definition and implementation at source code level. After that he can build the class-ob ject class by using the COC-generator. This class can be specialized by derivation as necessary. Finally the class-ob ject manager loads the code of the class and the generated class-ob ject class into the system and instantiates the class ob ject.

All further tasks for managing ob jects of the loaded class have to be done by the new class object. For the implementation of class objects we have modified the mechanisms for object identication and method invocation.

Alternative Ob ject Access resp. Method Invocation

All dynamically created $C++$ objects are referenced through the address of their data area [Stroustrup90]. Calls to virtual methods are performed indirectly via a virtual method table (VMT) referenced by a special component in the ob ject's data area.

To obtain location transparency for ob jects we have modied this mechanism:

- \bullet Because different kinds of objects have to be handled differently (e.g. local or remote ob jects), potentially each ob ject has to get its own VMT to meet the ob ject's special requirements. Grouping of objects within the class to use the same VMT is possible.
- Class-ob jects manage all necessary information about the ob jects of its class. The creation mechanism for objects was modified in such a way, that it delivers not a pointer to an ob ject but a pointer to an ob ject description entry managed by the class ob ject. As the first component in each object description entry the pointer to the $(modified)$ VMT is stored so that the compiler generated method invocation is still working.

Figure 4 demonstrates the resulting procedure of method invocation. In the current implementation the COC-generator creates a class-ob ject method corresponding to each method of the appropriate class. The new VMT refers to the class-ob ject method instead to the ob ject's method. Within that class-ob ject method decisions can be made, how to proceed with the ob ject's method invocation. Using the ob ject description entry, the class ob ject can detect if the ob ject exists locally or remotely, if the caller and the callee are related to the same or to different threads, etc.

Figure 4. The Modied Structure for Ob ject Invocation

A typical sequence of actions could be as follows:

- 1. register ob ject invocation, for logging ob jects state,
- 2. check access permissions
- 3. check ob ject's location and ob ject-activity relations,
- 4. invoke method, either by a simple call or by an RPC,
- 5. register end of method invocation,
- 6. deliver output parameters.

To change, extend or reduce these steps, the system developer has to specialize the automatically generated class-ob ject class and to tell the class-ob ject manager to use this new class instead. For instance, in the current implementation only synchronous method invocation is supported, performed by a local call or an RPC. If it is necessary to modify this meta property of ob jects, the class ob ject has to be modied (changing infrastructure).

A similar approach to achieve dynamic adaptability by modifying the management and the invocation structure of $C++$ objects has been presented by the Object Binary Interface approach [Goldstein94]. However, in contrast to that work, our approach is based on using the available $C++$ compilers without the necessity of compiler modifications.

5 Related and Future Work

Whereas the projects PEACE and Tigger focus on building a framework for the development of statically tailored operating systems, Apertos, BirliX, or DAS [Goullon78], as we do, focus on dynamic adaptation. However, in contrast to those systems, we propose fine-grained adaptation, based on retaining the fine-grained structures which exist during software development within the running system. Furthermore, we are able to modify the infrastructure of regular ob jects, by modifying/exchanging the appropriate class ob jects.

Research projects in the field of operating systems employing the notion of meta objects are, for instance, Apertos, Tigger, AEON [Gowing95], and FlexMach(OMOS) [Orr92]. They are related to our pro ject in the respect, that our class ob jects and the class-ob ject manager are special meta objects. Further projects investigating new approaches to flexible operating systems are, for example, Bridge [Lucco94], and Spin [Bershad95]. These pro jects mainly explore secure ways to bring new code into the operating system kernel in order to adapt its behavior. Choices provides an loading mechanism to add new services to the running kernel based on run-time representations of classes. In contrast to that work the CHEOPS class-ob ject classes are specic to each class. In this way each class ob ject can perform exactly the services needed for the appropriate class.

During the next time some experiments with the implemented class ob jects have to be performed, in order to gain more experiences. The most suitable default COC functionality has still to be determined. This is necessary to prevent, that always specialized COC's have to be written. Till now, the whole prototype is located in a single address space and is running entirely in kernel mode. The support for application layer processes is still under construction. One further field of our investigations is the support of adaptation management by means of the class-ob ject architecture [Wohlrab97]. Beyond this, we plan to perform a series of efficiency tests, in order to determine where the overhead introduced by the class ob jects is too big to be compensated by their advantages. The result of these tests will consist of guidelines, which components may be implemented based on the class-ob ject architecture and which parts have to be realized in a traditional manner.

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